# Trigonometrically Fitted Improved Hybrid Method for Oscillatory Problems ${ }^{\dagger}$ 

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#### Abstract

Presented in this paper is a trigonometrically fitted scheme based on a class of improved hybrid method for the numerical integration of oscillatory problems. The trigonometric conditions are constructed through which a third algebraic order scheme is derived. Numerical properties of the scheme are analysed. A numerical experiment is conducted to validate the scheme. Results obtained reveal the superiority of the scheme over its equals in the literatur.e


Keywords: oscillatory solution; numerical scheme; trigonometrically fitted; hybrid method; trigonometric conditions; oscillatory problem

## 1. Introduction

Our interest in this paper is in the solution of a special class of second-order ordinary differential equations (ODEs) whose solution exhibits oscillatory behaviors. In short, the equation together with its boundary conditions (initial value problem (IVP)) takes the following form:

$$
\begin{equation*}
y^{\prime \prime}(x)=f(x, y(x)), y\left(x_{0}\right)=y_{0}, y^{\prime}\left(x_{0}\right)=y_{0}^{\prime} \tag{1}
\end{equation*}
$$

It is a special case of second ODEs because the right-hand-side of the main equation is independent of the $y^{\prime}$ component. Over the years, researchers' interest in this particular problem (1) has grown. This is largely due to its applicability in a number of areas in applied sciences including engineering, celestial mechanics, orbital mechanics, chemical kinetics, astrophysics, chemistry, physics and elsewhere [1-12]. Unfortunately, as important as the problems are (1), only a few of them could be solved analytically, hence the need for numerical schemes.

Traditional numerical schemes such as the Runge-Kutta methods, Runge-KuttaNyström methods, linear multistep method, etc., for solving second-order ODEs could solve (1) only with little accuracy and efficiency due to the behaviours of the solution. Research has shown that an adapted form of the traditional schemes could solve (1) with reduced error and better efficiency [5].

Recently, refs. [11,12] introduced in the literature a new numerical scheme that proved to be more promising in tackling (1). The methods are developed to be implemented in constant coefficient fashion. The method could perform better if adapted to specifically handle (1). This is the main motivation of this paper.

The remaining part of the paper is organized as follows: in Section 2, the proposed scheme is derived; results of numerical experiment are presented in Section 3; discussion of the results is presented in Section 4; and finally, the conclusion is given in Section 5.

## 2. The Scheme

The general form of the improved hybrid method is

$$
\begin{align*}
y_{n+1} & =\frac{3}{2} y_{n}-\frac{1}{2} y_{n-2}+h^{2} \sum_{i=1}^{s} b_{i} f\left(x_{n}+c_{i} h, Y_{i}\right) \\
Y_{i} & =\frac{1}{2}\left(2+c_{i}\right) y_{n}-\frac{1}{2} c_{i} y_{n-2}+h^{2} \sum_{i=j}^{s} a_{i, j} f\left(x_{n}+c_{j} h, Y_{j}\right), \tag{2}
\end{align*}
$$

where $y_{n+1}$ and $y_{n-2}$ are approximations for $y\left(x_{n+1}\right)$ and $y\left(x_{n-2}\right)$, respectively. $a_{i, j}, b_{i}$ and $c_{i}$ are coefficients of the method and they are real numbers. $i=1, \ldots, s$ and $i>j$, because the method is explicit. The coefficients can be summarized as follows (Table 1):

Table 1. General coefficients of the scheme.

| -2 | 0 |  |  |  |  |
| :---: | :---: | :---: | :--- | :--- | :--- |
| 0 | 0 | 0 |  |  |  |
| $c_{3}$ | $a_{31}$ | $a_{32}$ |  | 0 |  |
| $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ |  | $\vdots$ |
| $c_{m}$ | $a_{m 1}$ | $a_{m 2}$ |  | $\cdots$ | $a_{m m-1}$ |

### 2.1. Order Condition of the Scheme

Algebraic order condition of a method or scheme is a set of equations that causes the successive terms in the Taylor series expansion of local truncation error of the method to vanish. The order conditions of the scheme as derived and presented in [11,12] can be seen in the Table 2 below: Note: Conditions are in terms of the general coefficients in Table 1.

Table 2. Order Conditions.

| $\boldsymbol{t}$ | $\boldsymbol{\rho}(\boldsymbol{t})$ | Order Condition |
| :---: | :---: | :---: |
| $\tau$ | 0 | - |
| $\tau_{1}$ | 1 | - |
| $\tau_{2}$ | 2 | $\sum b_{i}=\frac{3}{2}$ |
| $t_{3,1}$ | 3 | $\sum b_{i} c_{i}=-\frac{1}{2}$ |
| $t_{4,1}$ | 4 | $\sum b_{i} c_{i}^{2}=\frac{3}{4}$ |
| $t_{4,2}$ | 5 | $\sum b_{i} a_{i, j}=-\frac{1}{8}$ |
| $t_{5,1}$ | $\sum b_{i} c_{i}^{3}=-\frac{3}{4}$ |  |
| $t_{5,2}$ |  | $\sum b_{i} c_{i} a_{i, j}=\frac{3}{8}$ |
| $t_{5,3}$ |  | $\sum b_{i} a_{i, j} c_{j}=\frac{5}{24}$ |
| $t_{6,1}$ | $\sum b_{i} c_{i}^{4}=\frac{11}{10}$ |  |
| $t_{6,2}$ |  | $\sum b_{i} c_{i}^{2} a_{i, j}=\frac{11}{20}$ |
| $t_{6,3}$ |  | $\sum b_{i} c_{i} a_{i, j} c_{j}=\frac{41}{60}$ |
| $t_{6,4}$ | $\sum b_{i} a_{i, j} a_{i, k}=\frac{3}{16}$ |  |
| $t_{6,5}$ | $\sum b_{i} a_{i, j} c_{j}^{2}=-\frac{87}{360}$ |  |
| $t_{6,6}$ | $\sum b_{i} a_{i, j} a_{j, k}=\frac{21}{240}$ |  |

### 2.2. Trigonometric Conditions

Suppose we apply the scheme (2) to solve problem (1) whose solution is a linear combination of $\left\{x^{j} \exp (\alpha x), x^{j} \exp (-\alpha x)\right\}$, exactly, where $\alpha$ is real or complex. However, here, we are interested in the complex value. Assume the solution is $\exp (i \alpha x)$, where i is imaginary. Then, the trigonometric conditions are obtained as follows:

$$
\begin{aligned}
& \cos (z)-\frac{3}{2}+\frac{1}{2} \cos (2 z)+z^{2} \sum_{k=1}^{s} b_{k} \cos \left(c_{k} z\right)=0 \\
& \sin (z)-\frac{1}{2} \sin (2 z)+z^{2} \sum_{k=1}^{s} b_{k} \sin \left(c_{k} z\right)=0 \\
& \cos \left(c_{i} z\right)-1-\frac{1}{2} c_{i}+\frac{1}{2} c_{i} \cos (2 z)+z^{2} \sum_{j=1}^{i-1} a_{i j} \cos \left(c_{j} z\right)=0, \\
& \sin \left(c_{i} z\right)-\frac{1}{2} c_{i} \sin (z)+z^{2} \sum_{j=1}^{i-1} a_{i j} \sin \left(c_{j} z\right)=0
\end{aligned}
$$

where $z=\alpha h$.

### 2.3. Derivation of the Proposed Scheme

The proposed scheme is based on the "Three-step third-order hybrid method" presented in [11]:

Obviously, $s=3$ from Table 3. Now, substitute same in the trig. conditions while holding all the internal coefficients ( $c_{i}$ and $a_{i j}$ ) constant, we obtain

$$
\begin{aligned}
& \cos (z)=\frac{3}{2}-\frac{1}{2} \cos (2 z)-z^{2}\left(b_{1} \cos (2 z)+b_{2}+b_{3} \cos (3 z)\right) \\
& \sin (z)=\frac{1}{2} \sin (2 z)-z^{2}\left(-b_{1} \sin (2 z)-b_{3} \sin (3 z)\right) .
\end{aligned}
$$

That is a system of two equations in three unknown parameters, implying one degree of freedom. The one free parameter could be taken from Table 3 below, but we do not want any of the update stage coefficients to be constant. Hence, we choose one additional equation from Table 2 to augment the number of equations to be solved. The variable coefficients are obtained as follows:

$$
\begin{aligned}
& b_{1}=-\frac{3}{4} \frac{\sin (3 z) z^{2}+12 \sin (z) \cos (z)-12 \sin (z)}{z^{2}(9 \sin (2 z)-4 \sin (3 z))} \\
& b_{2}=\frac{1}{4} \frac{N_{1}}{z^{2}(9 \sin (2 z)-4 \sin (3 z))^{\prime}} \\
& b_{3}=\frac{1}{4} \frac{3 \sin (2 z) z^{2}+16 \sin (z) \cos (z)-16 \sin (z)}{z^{2}(9 \sin (2 z)-4 \sin (3 z))}
\end{aligned}
$$

where

$$
\begin{aligned}
N_{1}= & \\
& -3 \sin (2 z) \cos (3 z) z^{2}+3 \cos (2 z) z^{2} \sin (3 z)+36 \sin (z) \cos (z) \cos (2 z)- \\
& 16 \sin (z) \cos (z) \cos (3 z)-36 \sin (z) \cos (2 z)+16 \sin (z) \cos (3 z)- \\
& 36 \sin (2 z) \cos (z)+16 \cos (z) \sin (3 z)-18 \cos (2 z) \sin (2 z)+8 \cos (2 z) \sin (3 z)+ \\
& 54 \sin (2 z)-24 \sin (3 z) .
\end{aligned}
$$

However, observe that as $z \rightarrow 0$, there would be heavy cancellations. So, Taylor expansion of the coefficients would be used. The corresponding values after the expansion are:

$$
\begin{aligned}
& b_{1}=\frac{3}{8}+\frac{39 z^{4}}{320}-\frac{2627 z^{6}}{16128}+O\left(z^{8}\right) \\
& b_{2}=\frac{29}{24}+\frac{3 z^{4}}{320}+\frac{26309 z^{6}}{725760}+O\left(z^{8}\right) \\
& b_{3}=-\frac{1}{12}-\frac{13 z^{4}}{240}+\frac{2627 z^{6}}{36288}+O\left(z^{8}\right)
\end{aligned}
$$

Table 3. Coefficients of ThHM3.

| -2 | 0 |  |  |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 |
| -3 | $\frac{5}{4}$ | $\frac{1}{4}$ | 0 |
|  | $\frac{3}{8}$ | $\frac{29}{24}$ | $-\frac{1}{12}$ |

### 2.4. Confirmation of Order of Convergence

The order of the scheme can be confirmed by substituting the coefficients back to algebraic order conditions to check the conditions that are recovered.

$$
\begin{aligned}
& \sum b_{i}=\frac{3}{2}+\frac{37 z^{4}}{480}-\frac{243 z^{6}}{4480}+O\left(z^{8}\right) \\
& \sum b_{i} c_{i}=-\frac{1}{2}-\frac{13 z^{4}}{160}+\frac{2627 z^{6}}{24192}+O\left(z^{8}\right) \\
& \sum b_{i} c_{i}^{2}=\frac{3}{4}+O\left(z^{14}\right) \\
& \sum b_{i} a_{i, j}=-\frac{1}{8}-\frac{13 z^{4}}{160}+\frac{2627 z^{6}}{24192}+O\left(z^{8}\right)
\end{aligned}
$$

It can be seen that the order conditions are recovered as $z$ approaches zero. Hence, by the order of convergence stated in [11], the scheme is of order three.

## 3. Numerical Results

In this section, the proposed scheme is validated by solving a few examples of problems with known exact solutions. The problems are:

## Problem 1 (Inhomogeneous Problem)

$\frac{d^{2} y(x)}{d x^{2}}=-y(x)+x, \quad y(0)=1, \quad y^{\prime}(0)=2$.
Exact solution: $\quad y(x)=\sin (x)+\cos (x)+x$.
Source: [1,11,12]. $x \in[0,100]$

Problem 2 (Duffing Problem)
$y^{\prime \prime}+y+y^{3}=F \cos (v x), \quad y(0)=0.200426728067$,
$y^{\prime}(0)=0$. where $F=0.002$ and $v=1.01$.
Exact solution: $\quad y(x)=\sum_{i=0}^{4} v_{2 i+1} \cos [(2 i+1) v x]$,
where $v_{1}=0.200179477536, v_{3}=0.246946143 \times 10^{-3}$,
$v_{5}=0.304014 \times 10^{-6}, v_{7}=0.374 \times 10^{-9}$, and
$v_{9}<10^{-12} \alpha=1$.
Source: [11,12]. $x \in[0,100]$

## 4. Discussion

The proposed scheme is applied on two test problems alongside its base method. The problems are linear nonhomogeneous and nonlinear homogeneous, respectively. The methods maintained a remarkable level of accuracy in solving the problems. It is also obvious that as $h$ approaches zero, the max. error decreases, which indicates convergence. That is to say, the fitted scheme converges faster, as its error decreases more than that of the base method, especially on Problem 2. See Tables 4 and 5.

Table 4. Maximum Error for Problem 1.

| $\boldsymbol{h}$ | TThMH | ThHM |
| :---: | :---: | :---: |
| 0.125 | $1.09000000 \times 10^{-05}$ | $9.14000000 \times 10^{-05}$ |
| 0.0625 | $6.81778300 \times 10^{-07}$ | $5.74000000 \times 10^{-06}$ |
| 0.03125 | $4.27171140 \times 10^{-08}$ | $3.59427562 \times 10^{-07}$ |
| 0.015625 | $2.67374400 \times 10^{-09}$ | $2.24843520 \times 10^{-08}$ |
| 0.0078125 | $1.67950000 \times 10^{-10}$ | $1.40043000 \times 10^{-09}$ |

Table 5. Maximum Error for Problem 2.

| $\boldsymbol{h}$ | TThMH | ThHM |
| :---: | :---: | :---: |
| 0.125 | $1.53000000 \times 10^{-06}$ | $1.13900000 \times 10^{-05}$ |
| 0.0625 | $9.93512828 \times 10^{-08}$ | $7.19084606 \times 10^{-07}$ |
| 0.03125 | $6.33294855 \times 10^{-09}$ | $4.51587658 \times 10^{-08}$ |
| 0.015625 | $4.00945820 \times 10^{-10}$ | $2.83063643 \times 10^{-09}$ |
| 0.0078125 | $2.63143000 \times 10^{-11}$ | $1.78347304 \times 10^{-10}$ |

## 5. Conclusions

A fitted numerical scheme for numerical integration of oscillatory problems is proposed and derived. The scheme is validated using test problems whose analytical solutions are known. From the results obtained, it can be concluded that the fitted form of the improved hybrid method can be more promising in tackling oscillatory problems, especially nonlinear ones.

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## Abbreviations

The following abbreviations are used in this manuscript:
ThHM The three-step two-stage improved hybrid method derived in [11]
TThHM The proposed scheme presented in this paper

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